

## Hot Glue Kit Module Command List

Utku Culha, Biologically Inspired Robotics Laboratory, University of Cambridge

| Command String | Definition   | Response  |
|----------------|--|---|
| <b>H</b>       | Module ping command. Send to check which modules are on and ready for communication  | The modules which are on will respond with the following structure: '+M#' where # is the module number. E.g. '+M1'  |
| <b>M#</b>      | Module selection command. # should be replaced with a module number. E.g. 'M1'   | The selected module will respond '+M# S' where # is the module number. E.g. '+M1 S'. Once a module is selected, it will only respond once!  |
| <b>MA#</b>     | Group selection command. # should be replaced with a group number. E.g. 'MA1'  | The selected modules in the group will respond '+M# A' where # is the module number. '+M1 A'. The modules will respond only once when selected!   |
| <b>A</b>       | This initiates alternating motion behavior. After this command module waits for 2 numeric value command to define the alternating points. These values are defined as the number of motor turns.   | The module responds '+A'  |
| <b>D</b>       | This initiates single motor turn behavior. After this command, module waits for 1 numeric value command which is defined as the number of turns desired.   | The module responds '+D'  |
| <b>P</b>       | Phase delay command. This makes the module delay for a time before starting to move the motor. After this command, module waits for 1 numeric value command which defines the amount of time in seconds that the module will wait before starting to move the motor. | The module responds '+P'  |
| <b>numeric</b> | Only after A, D or P commands, a numeric command should be sent. It can be a positive or negative number with 2 decimal points. E.g. '2.5' or '-1'   | The module responds according to behavior command. If it was 'A', after the first numeric command it responds '+A1: <i>numeric</i> ' and after the second it responds '+A2: <i>numeric</i> '. If it was 'D', it responds '+D: <i>numeric</i> '. If it was 'P', it responds '+P: <i>numeric</i> '. |
| <b>X</b>       | Execute behavior command. After module is configured with chosen motor behavior and phase delay, this command starts to move the motor accordingly.  | The module responds '+X'  |
| <b>S</b>       | Stop behavior command. This command will stop moving the motor.  | The module responds '+S'  |
| <b>R</b>       | Reset module command. This will reset all the previously sent configurations such as motor turns and phase time.   | The module responds '+R'  |
| <b>E</b>       | End connection command. This command will end the communication with a module. Module will continue working but will not respond to any other commands until it is selected again.   | The module responds '+E'  |